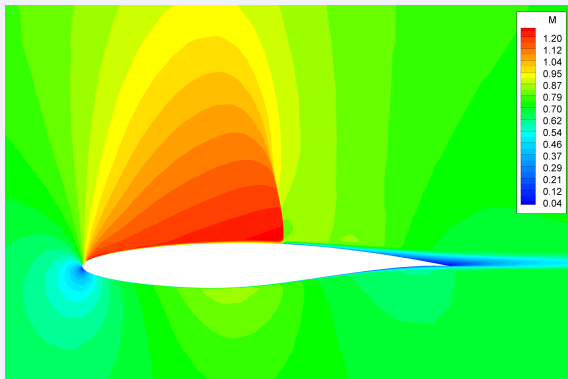


# Aerodynamics I

## Compressible flow past an airfoil



*transonic flow past the RAE-2822 airfoil ( $M = 0.73$ ,  $Re = 6.5 \times 10^6$ ,  $\alpha = 3.19^\circ$ )*



# Potential equation in compressible flows



## Full potential theory

Let us introduce a velocity potential (no vorticity is present  $\nabla \times \mathbf{v} = 0$ ):

$$\mathbf{v} = \nabla \Phi \quad \xrightarrow{2D} \quad u = \frac{\partial \Phi}{\partial x} \quad v = \frac{\partial \Phi}{\partial y} \quad (1.1)$$

Continuity equation can be transformed:

$$\nabla \cdot (\rho \mathbf{v}) = \rho \nabla \cdot \mathbf{v} + \mathbf{v} \cdot \nabla \rho = 0 \quad \rightarrow \quad \rho \nabla^2 \Phi + \nabla \Phi \cdot \nabla \rho = 0 \quad (1.2)$$

From momentum equation:

$$-\frac{1}{\rho} \nabla p = \mathbf{v} \cdot \nabla \mathbf{v} = \nabla \left( \frac{V^2}{2} \right) + (\nabla \times \mathbf{v}) \times \mathbf{v} \quad (1.3)$$

Since vorticity  $\nabla \times \mathbf{v}$  is zero :

$$(\nabla \times \mathbf{v}) \times \mathbf{v} = 0 \quad \rightarrow \quad dp = -\frac{\rho}{2} d(V^2) = -\frac{\rho}{2} d(\nabla \Phi \cdot \nabla \Phi) \quad (1.4)$$

Using equation for speed of sound (isentropic relation):

$$dp = c^2 d\rho \quad \rightarrow \quad d\rho = -\frac{\rho}{2c^2} d(\nabla \Phi \cdot \nabla \Phi) \quad (1.5)$$



## Full potential theory

Gradient of density can be obtained fro equation:

$$\nabla \rho = -\frac{\rho}{2c^2} \nabla (\nabla \Phi \cdot \nabla \Phi) = -\frac{\rho}{c^2} \nabla \Phi \cdot \nabla \nabla \Phi \quad (1.6)$$

for 2D:

$$\frac{\partial \rho}{\partial x} = -\frac{\rho}{c^2} \left[ \frac{\partial \Phi}{\partial x} \frac{\partial^2 \Phi}{\partial x^2} + \frac{\partial \Phi}{\partial y} \frac{\partial^2 \Phi}{\partial x \partial y} \right]$$

$$\frac{\partial \rho}{\partial y} = -\frac{\rho}{c^2} \left[ \frac{\partial \Phi}{\partial x} \frac{\partial^2 \Phi}{\partial x \partial y} + \frac{\partial \Phi}{\partial y} \frac{\partial^2 \Phi}{\partial y^2} \right] \quad (1.7)$$

$$(1.8)$$

after substituting into (1.2):

$$\rho \nabla^2 \Phi - \frac{\rho}{c^2} \nabla \Phi \cdot (\nabla \Phi \cdot \nabla \nabla \Phi) = 0 \quad (1.9)$$

for 2D:

$$\frac{\partial^2 \Phi}{\partial x^2} + \frac{\partial^2 \Phi}{\partial y^2} - \frac{1}{c^2} \left[ \left( \frac{\partial \Phi}{\partial x} \right)^2 \frac{\partial^2 \Phi}{\partial x^2} + \left( \frac{\partial \Phi}{\partial y} \right)^2 \frac{\partial^2 \Phi}{\partial y^2} + 2 \frac{\partial \Phi}{\partial x} \frac{\partial \Phi}{\partial y} \frac{\partial^2 \Phi}{\partial x \partial y} \right] = 0 \quad (1.10)$$

## Full potential theory

After transformation equation (1.10) takes following form:

$$\left[1 - \frac{1}{c^2} \left(\frac{\partial \Phi}{\partial x}\right)^2\right] \frac{\partial^2 \Phi}{\partial x^2} + \left[1 - \frac{1}{c^2} \left(\frac{\partial \Phi}{\partial y}\right)^2\right] \frac{\partial^2 \Phi}{\partial y^2} = \frac{2}{c^2} \frac{\partial \Phi}{\partial x} \frac{\partial \Phi}{\partial y} \frac{\partial^2 \Phi}{\partial x \partial y}$$

(1.11)

Using energy integral the relation for speed of sound can be obtained:

$$c^2 = c_0^2 - \frac{k-1}{2} \left[ \left(\frac{\partial \Phi}{\partial x}\right)^2 + \left(\frac{\partial \Phi}{\partial y}\right)^2 \right]$$

(1.12)

Equations (1.11) and (1.12) are equation of full potential theory. They allow to simulate compressible flows with weak (izentropic relations are used!) shock waves.



## Linearized equations of small disturbances potential

Equations (1.11) and (1.12) can be further simplified by introducing potential of small disturbances and using linearization.

$$\mathbf{v} = \mathbf{v}_\infty + \tilde{\mathbf{v}} \quad (1.13)$$

where:

$$\mathbf{v} = [u, v]^T, \quad \mathbf{v}_\infty = [V_\infty, 0]^T, \quad \tilde{\mathbf{v}} = [\tilde{u}, \tilde{v}]^T$$

Let us define potential of disturbances  $\phi$  :

$$\tilde{\mathbf{v}} = \nabla\phi \quad \rightarrow \quad \Phi = V_\infty x + \phi \quad (1.14)$$

After substituting into equation (1.11):

$$\left[ c^2 - \left( V_\infty + \frac{\partial\phi}{\partial x} \right)^2 \right] \frac{\partial^2\phi}{\partial x^2} + \left[ c^2 - \left( \frac{\partial\phi}{\partial y} \right)^2 \right] \frac{\partial^2\phi}{\partial y^2} = 2 \left( V_\infty + \frac{\partial\phi}{\partial x} \right) \frac{\partial\phi}{\partial y} \frac{\partial^2\phi}{\partial x\partial y} \quad (1.15)$$

## Linearized equations of small disturbances potential

In order to simplify the (1.15) it is convenient to use form based on velocity not the potential:

$$\left[ c^2 - (V_\infty + \tilde{u})^2 \right] \frac{\partial \tilde{u}}{\partial x} + \left[ c^2 - \tilde{v}^2 \right] \frac{\partial \tilde{v}}{\partial y} = 2(V_\infty + \tilde{u}) \tilde{v} \frac{\partial \tilde{u}}{\partial y} \quad (1.16)$$

Equation (1.12) takes form:

$$c^2 = c_\infty^2 - \frac{k-1}{2} (2V_\infty \tilde{u} + \tilde{u}^2 + \tilde{v}^2) \quad (1.17)$$

After substitution (1.17) into (1.16) and transformation:

$$\begin{aligned} (1 - M_\infty^2) \frac{\partial \tilde{u}}{\partial x} + \frac{\partial \tilde{v}}{\partial y} &= M_\infty^2 \left[ (k+1) \frac{\tilde{u}}{V_\infty} + \frac{k+1}{2} \frac{\tilde{u}^2}{V_\infty^2} + \frac{k-1}{2} \frac{\tilde{v}^2}{V_\infty^2} \right] \frac{\partial \tilde{u}}{\partial x} \\ &+ M_\infty^2 \left[ (k+1) \frac{\tilde{v}}{V_\infty} + \frac{k+1}{2} \frac{\tilde{v}^2}{V_\infty^2} + \frac{k-1}{2} \frac{\tilde{u}^2}{V_\infty^2} \right] \frac{\partial \tilde{v}}{\partial y} \\ &+ M_\infty^2 \left[ \frac{\tilde{v}}{V_\infty} \left( 1 + \frac{\tilde{u}}{V_\infty} \right) \left( \frac{\partial \tilde{u}}{\partial x} + \frac{\partial \tilde{v}}{\partial x} \right) \right] \end{aligned} \quad (1.18)$$

## Linearized equations of small disturbances potential

Assuming small disturbances (valid for thin airfoils at small angles of attack):

$$\frac{\tilde{u}}{V_\infty} \ll 1 \quad \frac{\tilde{v}}{V_\infty} \ll 1 \quad (1.19)$$

Equation (1.18) can be transformed to a form where only linear terms are present (it is assumed that it is valid for  $M_\infty < 0.8$  and  $1.2 < M_\infty < 5$ ):

$$(1 - M_\infty^2) \frac{\partial \tilde{u}}{\partial x} + \frac{\partial \tilde{v}}{\partial y} = 0 \quad (1.20)$$

After substitution of the potential function:

$$(1 - M_\infty^2) \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = 0 \quad (1.21)$$

This equation is elliptic for  $M_\infty < 1$  and hyperbolic for  $M_\infty > 1$ .



## Pressure coefficient for linearized equations

Pressure coefficient is defined by:

$$C_p \equiv \frac{p - p_\infty}{q_\infty} \quad \text{gdzie:} \quad q_\infty = \frac{\rho_\infty V_\infty^2}{2} \quad (1.22)$$

Equation (1.22) can be transformed using:

$$q_\infty = \frac{\rho_\infty V_\infty^2}{2} = \frac{k p_\infty}{2} \left( \frac{\rho_\infty}{k p_\infty} \right) V_\infty^2 = \frac{k}{2} p_\infty M_\infty^2 \quad (1.23)$$

The formula for pressure coefficients takes then form:

$$C_p = \frac{2}{k M_\infty^2} \left( \frac{p}{p_\infty} - 1 \right) \quad (1.24)$$

For simplifications we will use izentropic relation::

$$\frac{p}{p_\infty} = \left( \frac{T}{T_\infty} \right)^{\frac{k}{k-1}} \quad (1.25)$$

## Pressure coefficient for linearized equations

From energy integral:

$$\frac{V^2}{2} + c_p T = \frac{V_\infty^2}{2} + c_p T_\infty \quad \rightarrow \quad T - T_\infty = \frac{k-1}{2kR} (V_\infty^2 - V^2) \quad (1.26)$$

Using definition of the disturbance velocity (1.13) we can obtain:

$$\frac{T}{T_\infty} = 1 - \frac{k-1}{2} M_\infty^2 \left( \frac{2\tilde{u}}{V_\infty} + \frac{\tilde{u}^2 + \tilde{v}^2}{V_\infty^2} \right) \quad (1.27)$$

After substituting:

$$\frac{p}{p_\infty} = \left[ 1 - \frac{k-1}{2} M_\infty^2 \left( \frac{2\tilde{u}}{V_\infty} + \frac{\tilde{u}^2 + \tilde{v}^2}{V_\infty^2} \right) \right]^{\frac{k}{k-1}} \quad (1.28)$$

It can be simplified by expanding using Taylor series and discarding higher order terms:

$$\frac{p}{p_\infty} = (1 - r)^{\frac{k}{k-1}} = 1 - \frac{k}{k-1} r + \dots \quad (1.29)$$

$$\frac{p}{p_\infty} \approx 1 - \frac{k}{2} M_\infty^2 \left( \frac{2\tilde{u}}{V_\infty} + \frac{\tilde{u}^2 + \tilde{v}^2}{V_\infty^2} \right) \quad (1.30)$$

## Pressure coefficient for linearized equations

Substituting (1.30) into (1.24):

$$C_p = -\frac{2\tilde{u}}{V_\infty} - \frac{\tilde{u}^2 + \tilde{v}^2}{V_\infty^2} \quad (1.31)$$

For small disturbances (1.19):

$$\frac{\tilde{u}^2 + \tilde{v}^2}{V_\infty^2} \ll \frac{2\tilde{u}}{V_\infty} \quad (1.32)$$

Finally, we can obtain the simplified relation for pressure coefficient:

$$C_p = -\frac{2\tilde{u}}{V_\infty} \quad (1.33)$$

The relations are valid for both, subsonic and supersonic flows.

## Prandtl–Glauert rule

Let us consider subsonic flow ( $M_\infty < 1$ ) which is described by linearized equations of small disturbances potential. We can define the coefficient:

$$\beta \equiv \sqrt{1 - M_\infty^2} \quad (1.34)$$

equation (1.21) can be then written in form:

$$\beta^2 \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = 0 \quad (1.35)$$

This equation can be transformed to Laplace equation by transformation applied to the reference coordinates, e.g.:

$$\xi = x \quad \eta = \beta y \quad \rightarrow \quad \frac{\partial}{\partial x^2} = \frac{\partial}{\partial \xi^2} \quad \frac{\partial}{\partial y^2} = \beta^2 \frac{\partial}{\partial \eta^2} \quad (1.36)$$

After substituting into (1.35):

$$\beta^2 \frac{\partial^2 \varphi}{\partial \xi^2} + \beta^2 \frac{\partial^2 \varphi}{\partial \eta^2} = 0 \quad \rightarrow \quad \frac{\partial^2 \varphi}{\partial \xi^2} + \frac{\partial^2 \varphi}{\partial \eta^2} = 0 \quad (1.37)$$



## Prandtl–Glauert rule

What is a difference between  $\phi$  and  $\varphi$  ?

Let us assume that the boundary of the airfoil on the plane  $x - y$  is defined by function  $y = f(x)$ . Boundary condition for the airfoil (normal velocity is equal zero) then can be defined:

$$\frac{d}{dx} f(x) = \frac{\tilde{v}}{V_\infty + \tilde{u}} \approx \frac{\tilde{v}}{V_\infty} \quad \rightarrow \quad \tilde{v} = \frac{\partial \phi}{\partial y} = V_\infty \frac{d}{dx} f(x) \quad (1.38)$$

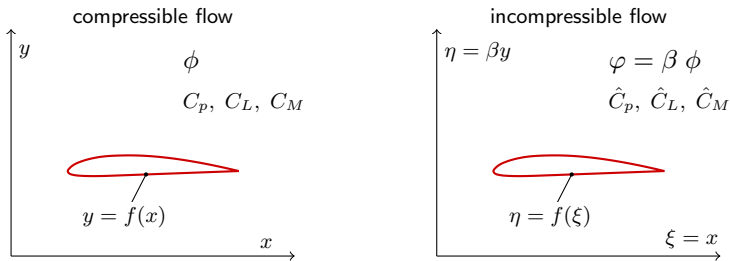
In similar way for  $\xi - \eta$ :

$$\frac{d}{d\xi} \hat{f}(\xi) = \frac{\hat{v}}{V_\infty + \hat{u}} \approx \frac{\hat{v}}{V_\infty} \quad \rightarrow \quad \hat{v} = \frac{\partial \varphi}{\partial \eta} = V_\infty \frac{d}{d\xi} \hat{f}(\xi) \quad (1.39)$$

Assuming that airfoils in  $x - y$  and  $\xi - \eta$  are similar then  $\hat{f} = f$ .

$$\frac{\partial \varphi}{\partial \eta} = \frac{1}{\beta} \frac{\partial \varphi}{\partial y} = \frac{\partial \phi}{\partial y} \quad \rightarrow \quad \varphi = \beta \phi \quad (1.40)$$

## Prandtl-Glauert rule



Using (1.33) it is possible to obtain relation for  $C_p$ :

$$C_p = -\frac{\tilde{u}}{V_\infty} = -\frac{1}{V_\infty} \frac{\partial \phi}{\partial x} = -\frac{1}{\beta V_\infty} \frac{\partial \varphi}{\partial x} = -\frac{\hat{u}}{\beta V_\infty} = \frac{1}{\beta} \hat{C}_p \quad (1.41)$$

Since moment and lift coefficients are integrals of  $C_p$  finally we can obtain:

$$C_p = \frac{\hat{C}_p}{\sqrt{1 - M_\infty^2}} \quad C_L = \frac{\hat{C}_L}{\sqrt{1 - M_\infty^2}} \quad C_M = \frac{\hat{C}_M}{\sqrt{1 - M_\infty^2}} \quad (1.42)$$



## Other high order rules

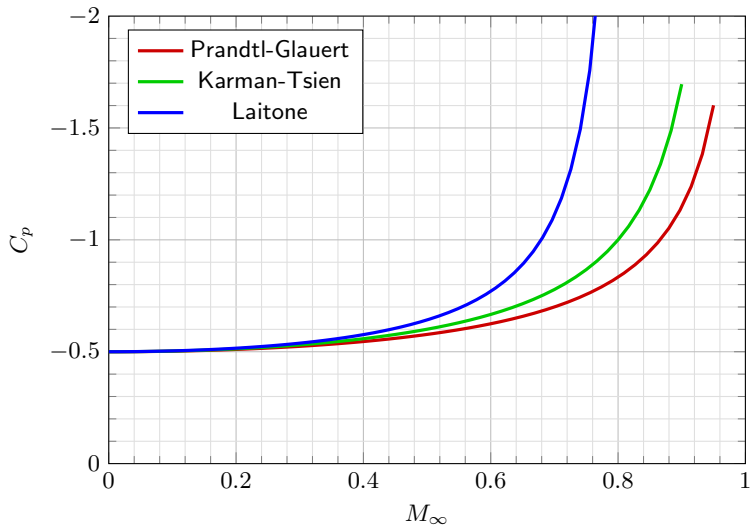
Karman-Tsien rule:

$$C_p = \frac{\hat{C}_p}{\sqrt{1 - M_\infty^2} + \frac{M_\infty^2}{1 + \sqrt{1 - M_\infty^2}} \frac{\hat{C}_p}{2}} \quad (1.43)$$

Laitone rule:

$$C_p = \frac{\hat{C}_p}{\sqrt{1 - M_\infty^2} + \frac{M_\infty^2 (1 + \frac{k-1}{2} M_\infty^2)}{2 \sqrt{1 - M_\infty^2}} \hat{C}_p} \quad (1.44)$$

## Other high order rules







## Linearized supersonic flow

In supersonic flow ( $M_\infty > 1$ ) the equation (1.21) can be written:

$$\lambda^2 \frac{\partial^2 \phi}{\partial x^2} - \frac{\partial^2 \phi}{\partial y^2} = 0 \quad \text{where:} \quad \lambda = \sqrt{M_\infty^2 - 1} \quad (1.45)$$

This is the wave equation where the wave propagation speed is equal  $\lambda$ . The general solution to this problem has form:

$$\phi = f_+(x + \lambda y) + f_-(x - \lambda y) \quad (1.46)$$

where  $f_+$  i  $f_-$  are arbitrarily chosen functions. The values of  $f_+$  and  $f_-$  are constant along lines defined by:

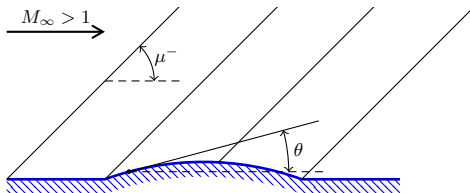
$$x + \lambda y = \text{const} \quad x - \lambda y = \text{const} \quad (1.47)$$

Such lines are called **characteristics** of the wave equation. the angle of inclination of the characteristics can be obtained from (1.46):

$$\frac{dy}{dx} = \pm \frac{1}{\lambda} = \pm \frac{1}{\sqrt{M_\infty^2 - 1}} = \text{tg}(\mu^\pm) \quad (1.48)$$

Characteristics of the equation (1.45) are identical to the Mach lines.

## Linearized supersonic flow



The boundary condition for zero normal velocity must be satisfied on the boundary of the domain or airfoil':

$$\operatorname{tg}(\theta) = \frac{\tilde{v}}{V_\infty + \tilde{u}} \approx \frac{\tilde{v}}{V_\infty} \quad (1.49)$$

Using general solution to the wave equation (1.46):

$$\begin{aligned} \tilde{u} &= \frac{\partial \phi}{\partial x} = f'_+ + f'_- & \tilde{v} &= \frac{\partial \phi}{\partial y} = \lambda (f'_+ - f'_-) \rightarrow \\ & & \rightarrow \tilde{u} &= \frac{\tilde{v}}{\lambda} \left[ \frac{f'_+ + f'_-}{f'_+ - f'_-} \right] \end{aligned} \quad (1.50)$$



## Linearized supersonic flow

Using boundary condition (1.49) we can obtain:

$$\tilde{v} = V_\infty \operatorname{tg}(\theta) \quad \rightarrow \quad \tilde{u} \approx \frac{V_\infty \theta}{\lambda} \left[ \frac{f'_+ + f'_-}{f'_+ - f'_-} \right] \quad (1.51)$$

After substituting (1.51) into (1.33):

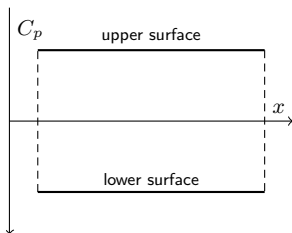
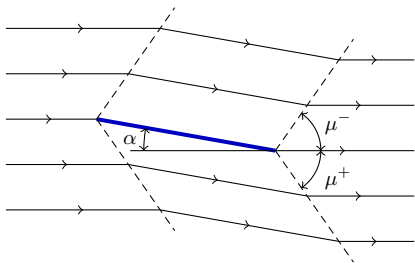
$$C_p = - \frac{2\theta}{\sqrt{M_\infty^2 - 1}} \left[ \frac{f'_+ + f'_-}{f'_+ - f'_-} \right] \quad (1.52)$$

Functions  $f_+$  and  $f_-$  can be chosen arbitrarily. In order to simplify the problem we will consider only two cases:  $f_+$  is constant or  $f_-$  is constant. Since characteristics are identical to Mach lines their type (sign) should be chosen such that the disturbances will be propagated with the flow.

$$C_p^{U/L} = \pm \frac{2\theta}{\sqrt{M_\infty^2 - 1}} \quad (1.53)$$

wher:  $U$  – upper airfoil surface,  $L$  – lower airfoil surface

## Linearized supersonic flow - flat plate



Upper surface – characteristic  $\mu^-$  and  $\theta = -\alpha$  :

$$C_p^U = -\frac{2\alpha}{\sqrt{M_\infty^2 - 1}} \quad (1.54)$$

Lower surface – characteristic  $\mu^+$  and  $\theta = -\alpha$  :

$$C_p^L = \frac{2\alpha}{\sqrt{M_\infty^2 - 1}} \quad (1.55)$$

## Linearized supersonic flow - flat plate

Force coefficients in normal and tangent directions:

$$C_n = \frac{1}{l_{ac}} \int_0^{l_{ac}} (C_p^L - C_p^U) dx = \frac{4\alpha}{\sqrt{M_\infty^2 - 1}} \quad (1.56)$$

$$C_t = 0$$

Lift coefficient:

$$C_L = C_n \cos(\alpha) - C_t \sin(\alpha) \approx C_n \quad \rightarrow \quad C_L = \frac{4\alpha}{\sqrt{M_\infty^2 - 1}} \quad (1.57)$$

Drag coefficient:

$$C_D = C_n \sin(\alpha) + C_t \cos(\alpha) \approx C_n \alpha \quad \rightarrow \quad C_D = \frac{4\alpha^2}{\sqrt{M_\infty^2 - 1}} \quad (1.58)$$

In potential supersonic flow, there exists a nonzero drag force (in contrary to subsonic flow – s'Alembert paradox). This force is called **wave drag**.



## Linearized supersonic flow - flat plate

### Example:

Flow past a flat plate for  $\alpha = 10^\circ$ ,  $M_\infty = 2$  and  $p_\infty = 1$

Simplified theory - linearized supersonic flow:

$$C_L = \frac{4\alpha}{\sqrt{M_\infty^2 - 1}} = 0.403$$

$$C_D = \frac{4\alpha^2}{\sqrt{M_\infty^2 - 1}} = 0.0703$$

Exact theory based on the oblique shock wave and Prandtl-Meyer expansion:

$$C_L = 0.408$$

$$C_D = 0.0719$$

## Linearized supersonic flow - $dC_L/d\alpha$

Incompressible flows:

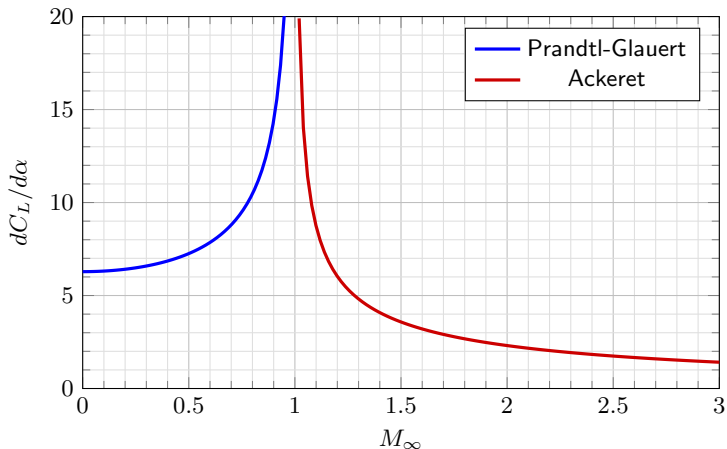
$$dC_L/d\alpha = 2\pi$$

Subsonic flows (P-G rule):

$$dC_L/d\alpha = 2\pi/\sqrt{M_\infty^2 - 1}$$

Supersonic flows:

$$dC_L/d\alpha = 4/\sqrt{M_\infty^2 - 1}$$

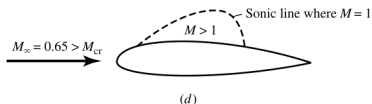
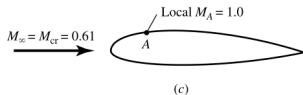
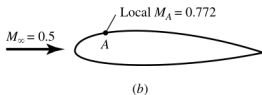
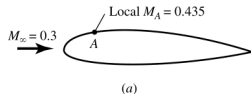




# Transonic flow past a 2D airfoil



## Critical Mach number



Critical Mach number  $M_{cr}$  is a Mach number of undisturbed flow  $M_\infty$  for which maximum of the local velocity at some point on the airfoil surface is equal to the speed of sound.

If  $M_\infty < M_{cr}$  then flow is fully subsonic (a i b)

If  $M_\infty > M_{cr}$  then there exists a supersonic flow region (d)

## Critical Mach number

For isentropic flow:

$$\frac{p}{p_\infty} = \frac{p}{p_0} \frac{p_0}{p_\infty} = \left( \frac{1 + \frac{k-1}{2} M_\infty^2}{1 + \frac{k-1}{2} M^2} \right)^{\frac{k}{k-1}} \quad (2.1)$$

Using (1.24):

$$C_p = \frac{2}{k M_\infty^2} \left[ \left( \frac{1 + \frac{k-1}{2} M_\infty^2}{1 + \frac{k-1}{2} M^2} \right)^{\frac{k}{k-1}} - 1 \right] \quad (2.2)$$

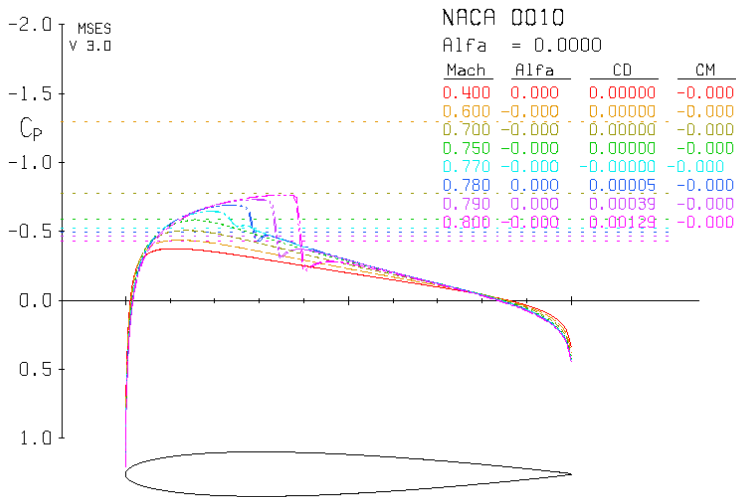
where  $M$  is local Mach number at some point on airfoil surface.

If  $M = 1$  then:

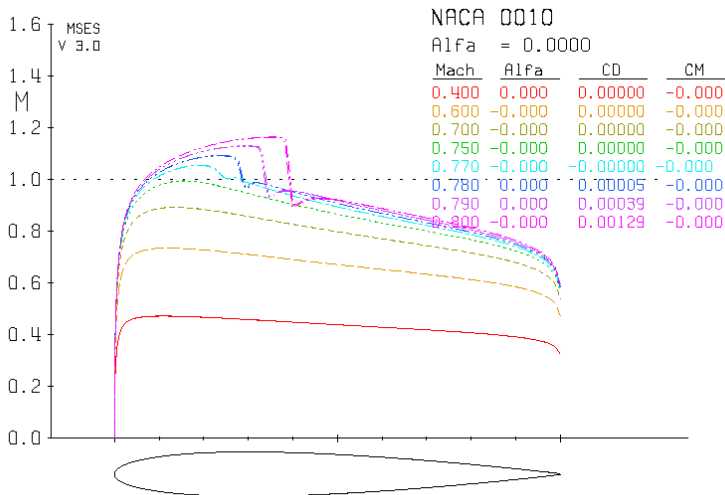
$$C_p^* = \frac{2}{k M_\infty^2} \left[ \left( \frac{1 + \frac{k-1}{2} M_\infty^2}{1 + \frac{k-1}{2}} \right)^{\frac{k}{k-1}} - 1 \right] \quad (2.3)$$

$C_p^*$  is a critical pressure coefficient. If at some point on airfoil surface  $C_p > C_p^*$  then at this point  $M > 1$ , otherwise if  $C_p < C_p^*$  then  $M < 1$ .

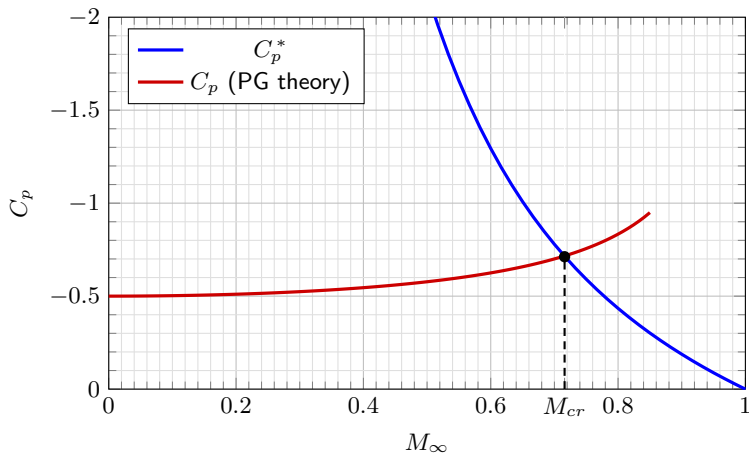
## Critical pressure coefficient



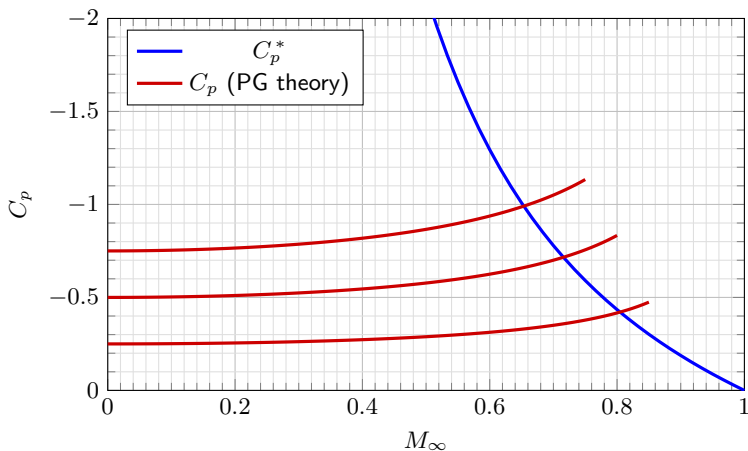
## Critical pressure coefficient



## Krytyczny współczynnik ciśnienia



## Critical pressure coefficient



## Critical pressure coefficient – airfoil thickness

