

Exercise 2

Transient Analysis = Time/history Analysis

Chanel section 60 x 40 x 1000 mm (5 mm wall thickness)

Material:

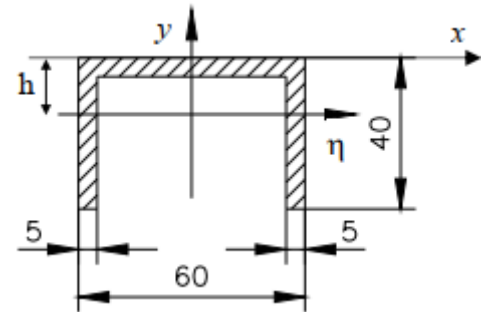
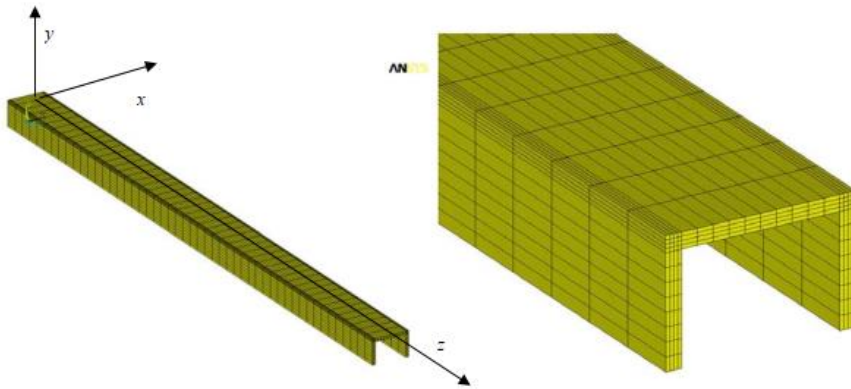
steel $E=200$ GPa, $\nu=0.3$,

$\rho=8000$ kg/m³

Damping of 5%

Cantilever beam from Exercise 2 (Modal Analysis):

Built-in in left end, load $F=500$ N, suddenly applied at the free end for 0.3 s and then removed for 0.2 s.



$$J=J_{\eta}=1.0097 \cdot 10^{-7} \text{m}^4$$

$$A=0.65 \cdot 10^{-3} \text{m}^2, \quad h=13.27 \text{mm}$$

Preliminary estimates:

1. **Damping:** First natural frequency – approx. 230 rad/s (35 Hz)

Vibration period - approx. 0.03 sec

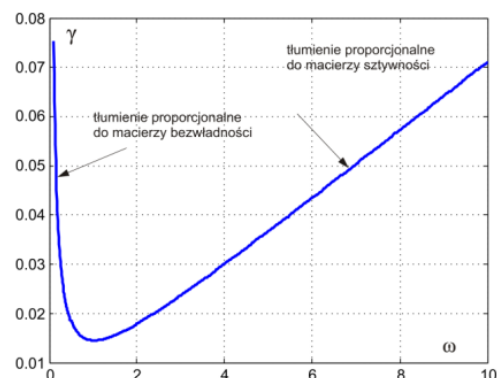
Tłumienie modalne jest skutecznym i wygodnym rozwiązaniem w sytuacji, gdy pomiary (lub założenia) określają udział tłumienia w poszczególnych postaciach własnych. Jest niezwykle korzystne (efektywne) w przypadkach, gdy analiza jest przeprowadzona metodą superpozycji modalnej.

Tłumienie proporcjonalne (Rayleigha) – najpowszechniej stosowanym modelem wyznaczania współczynnika tłumienia w tłumieniu wiskotycznym jest przyjęcie schematu, który postuluje przyjęcie macierzy tłumienia C jako zależnej od macierzy masowej M oraz macierzy sztywności K , czyli w postaci:

$$C = \alpha M + \beta K \quad (2.36)$$

From the Rayleigh damping model, assuming $\gamma=5\%$ (stiffness damping and no mass damping) (i.e. $\alpha = 0$):

$$\begin{cases} \alpha + \beta \omega_i^2 = 2\gamma_i \omega_i \\ \alpha + \beta \omega_j^2 = 2\gamma_j \omega_j \end{cases}$$



We have : $0 + \beta \cdot 230 = 2 \cdot 0.05$

So for FEM: **BETA = 0.000435**

ALPHA = 0

2. **Analysis time, division into parts and selection of integration steps.**
 - a. The first step is to load 500 N (4 forces of 125 N each).
Operating time 0.3 sec, i.e. approx. 10 vibration periods.
We assume 150 steps (i.e. 15 steps per period.)
 - b. The second step is to remove the load.
We count an additional 0.2 sec (up to 0.5 sec). We take 25 steps, which is very THICK... (we have just over 6 periods and only 25 steps).

Steps in ANSYS, cont. Exercise 2:

Solution:

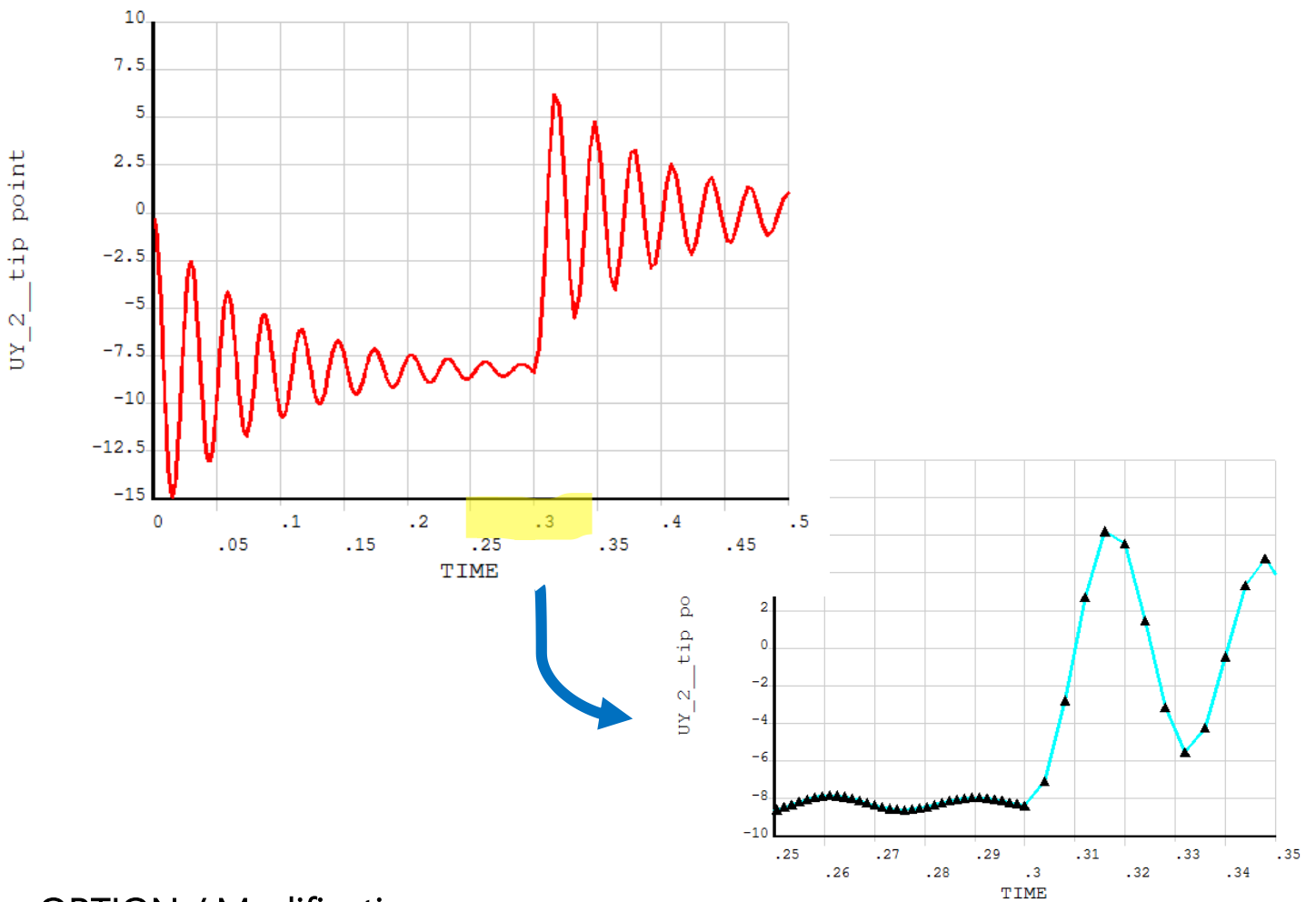
3. Setting the Analysis Type
 - a. *New Analysis* – (*Transient* followed by *Full*)
4. The first step of the load – time, steps, damping and load
 - a. Control settings (*Analysis Type - Solu Controls*) – up to 0.3 s in 150 steps, constant force loading, total 500N downhill
 - i. in the BASIC tab: *Time at end= 0.3 s, Number of substeps = 150*
 - ii. in the TRANSIENT *Stepped Loading tab* and *BETA = 0.000435*
 - b. **Apply Loads**-*Apply-Structural-Force*
 - i. at 4 points at the end (e.g. in Keypoints) $FY=-125N$
 - c. saving the details of this step (**LoadStep Options – Output Controls**) - attention !!
 - i. *Solu Printout –Every Substep*
 - ii. Write **LoadStep**: *Write LS file* (assign no. 1)
5. The next step of the load – time, steps, damping and load (and in the loop all further steps)
 - a. *Solu Controls* – up to 0.5 s in 25 steps, **load off**.
 - i. in the BASIC tab: *Time at end= 0.3 s, Number of substeps = 25*
 - ii. in the TRANSIENT b/z *Stepped Loading tab* and *BETA attenuation = 0.000435*
 - b. Define *Loads-DELETE-Structural-Force*
 - i. Best – in all KeyPoints
 - c. saving the details of this step (**LoadStep Options - Output Controls**) - attention !!
 - i. *Solu Printout –Every Substep*
 - ii. LoadStep write: *Write LS file* (assign no. 2)
6. Running the calculations of steps 1 and 2
 - a. **Solve** – From LS Files (*Starting 1, Ending 2*)

Visualization of results

7. TimeHistory Postprocessing (and further e.g. via icons)
 - a. 1st icon (plus) – selection of point and physical component for the chart
 - b. 3rd icon – make a chart
 - c. 4th icon – listing the results of the selected size
8. Plot *Controls – Style – Graphs*
 - a. *Modify Curves, Axis Range and Type (Aaxis), Grid*
 - b. white background *Plot Controls – Style – Colours -Reverse Video*

Illustration of the results:

1. Beam End Displacement Table (Selected Point)
2. Deformation dumps of several vibration steps (select a moment of time)
3. For a few moments of the DISPLACEMENT map (for the characteristic component of the



OPTION / Modification:

Load modification – damping and comparison with statics

$$\xi = \frac{\delta}{\sqrt{(2\pi)^2 + \delta^2}} \stackrel{dla \delta^2 \rightarrow 0}{\cong} \frac{\delta}{2\pi}$$

gdzie: $\delta = \ln(A_i / A_{i+1})$ - logarytmiczny dekrement tłumienia.